



Stability of a Fermionic $N + 1$ Particle System with Point Interactions

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Abstract: We prove that a system of N fermions interacting with an additional particle via point interactions is stable if the ratio of the mass of the additional particle to the one of the fermions is larger than some critical m^* . The value of m^* is independent of N and turns out to be less than 1. This fact has important implications for the stability of the unitary Fermi gas. We also characterize the domain of the Hamiltonian of this model, and establish the validity of the Tan relations for all wave functions in the domain.

1. Introduction

Models of particles with point interactions are ubiquitously used in physics as an idealized description whenever the range of the interparticle interactions is much shorter than other relevant length scales. They were introduced in the early days of quantum mechanics as models of nuclear interactions [2, 3, 14, 35, 38], but have proved useful in other branches of physics, like polarons (see [17] and references there) and cold atomic gases [40]. While the two-particle problem is mathematically completely understood [1], for more than two particles the existence of a self-adjoint Hamiltonian that is bounded from below and models pairwise point interactions is a challenging open problem. It is known that such a Hamiltonian can only exist for fermions with at most two components (or two different species of fermions), due to the Thomas effect [5, 30, 35, 39].

For $N \geq 2$, we consider here a system of N (spinless) fermions of mass 1, interacting with another particle of mass m via point interactions. The latter are characterized by a parameter $\alpha \in \mathbb{R}$, where $-1/\alpha$ is proportional to the scattering length of the pair interaction [1]. Purely formally, the Hamiltonian of the system can be thought of as

$$H = -\frac{1}{2m} \Delta_{x_0} - \frac{1}{2} \sum_{i=1}^N \Delta_{x_i} + \gamma \sum_{i=1}^N \delta(x_0 - x_i), \quad (1.1)$$

where $x_i \in \mathbb{R}^3$, and γ represents an infinitesimal coupling constant. Models of this kind have been studied extensively in the literature (see, e.g., [6–11, 13, 15, 18–23, 28, 37])

and can be defined via a suitable regularization procedure. More precisely, the formal expression (1.1) can be given a meaning in terms of a suitable quadratic form [7, 10, 15], which will be introduced in the next section. However, only in case the quadratic form is stable, i.e., bounded from below, does it give rise to a unique self-adjoint operator and hence gives a precise meaning to (1.1). We are interested in this question of stability. We shall show that there exists a critical mass m^* , independent of N , such that stability holds for $m > m^*$. The value of m^* is determined by a two-dimensional optimization problem of a certain analytic function. A numerical evaluation of the expression yields $m^* \approx 0.36$.

In particular, the system under consideration is stable for $m = 1$. This latter case is of particular importance, in view of constructing a model of a gas of spin 1/2 fermions close to the unitary limit, where the scattering length becomes much larger than the range of the interactions. For $N + 1$ such fermions, our result can be interpreted as proving the existence of such a model in the sector of total spin $(N - 1)/2$, i.e., 1 less than the maximal value. Of course stability holds trivially in the sector of total spin $(N + 1)/2$, since the particles do not interact in this case due to the total antisymmetry of the spatial part of the wave functions. We note that stability in other spin sectors is still an open problem, whose solution would be of great interest because of the relevance of the model for cold atomic gases (see [40] and references there). For its solution, it is necessary to understand the problem of stability for general systems of $N + M$ particles mutually interacting via point interactions. In the case $N = M = 2$, a numerical analysis suggests stability, see [19] for the case $m = 1$ and [12] for the full range of mass ratios where stability for the 2 + 1 problem holds, i.e., for $0.0735 < m < (0.0735)^{-1} \approx 13.6$ [5].

2. Model and Main Results

Because of translation invariance, it is convenient to separate the center-of-mass motion and to introduce relative coordinates $X = (mx_0 + \sum_{i=1}^N x_i)/(m + N)$, $y_i = x_i - x_0$ for $1 \leq i \leq N$ in the usual way. With their aid we can formally write the operator H in (1.1) as $H = H_{\text{cm}} + \frac{m+1}{2m} H_{\text{rel}}$, where $H_{\text{cm}} = -(2(m + N))^{-1} \Delta_X$ and

$$H_{\text{rel}} = - \sum_{i=1}^N \Delta_{y_i} - \frac{2}{m+1} \sum_{1 \leq i < j \leq N} \nabla_{y_i} \cdot \nabla_{y_j} + \tilde{\gamma} \sum_{i=1}^N \delta(y_i) \quad (2.1)$$

for $\tilde{\gamma} = 2m\gamma/(m + 1)$. The latter operator acts on purely anti-symmetric functions of N variables only.

The formal expression (2.1) can be given a meaning in terms of a suitable quadratic form [7, 10, 15], which will be introduced in the next subsection.

2.1. Quadratic form and stability. The model under consideration here is defined via a quadratic form F_α as follows. For $\mu > 0$ and $q_i \in \mathbb{R}^3$, $1 \leq i \leq N$, let

$$G(q_1, \dots, q_N) := \left(\sum_{i=1}^N q_i^2 + \frac{2}{m+1} \sum_{1 \leq i < j \leq N} q_i \cdot q_j + \mu \right)^{-1} \quad (2.2)$$

The quadratic form F_α has the domain

$$D(F_\alpha) = \left\{ u \in L_{\text{as}}^2(\mathbb{R}^{3N}) \mid u = w + G\xi, w \in H_{\text{as}}^1(\mathbb{R}^{3N}), \xi \in H_{\text{as}}^{1/2}(\mathbb{R}^{3(N-1)}) \right\} \quad (2.3)$$

where $G\xi$ is short for the function with Fourier transform

$$\widehat{G\xi}(q_1, \dots, q_N) = G(q_1, \dots, q_N) \sum_{i=1}^N (-1)^{i+1} \hat{\xi}(q_1, \dots, q_{i-1}, q_{i+1}, \dots, q_N) \quad (2.4)$$

and the subscript “as” indicates functions that are antisymmetric under permutations. For $u \in D(F_\alpha)$, we have

$$F_\alpha(u) = \left\langle w \left| -\sum_{i=1}^N \Delta_i - \frac{2}{m+1} \sum_{1 \leq i < j \leq N} \nabla_i \cdot \nabla_j + \mu \right| w \right\rangle - \mu \|u\|_{L^2(\mathbb{R}^{3N})}^2 + N \left(\alpha \|\xi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 + T_{\text{diag}}(\xi) + T_{\text{off}}(\xi) \right) \quad (2.5)$$

where

$$T_{\text{diag}}(\xi) := \int_{\mathbb{R}^{3(N-1)}} |\hat{\xi}(s, \vec{q})|^2 L(s, \vec{q}) \, ds \, d\vec{q}$$

$$T_{\text{off}}(\xi) := (N - 1) \int_{\mathbb{R}^{3N}} \hat{\xi}^*(s, \vec{q}) \hat{\xi}(t, \vec{q}) G(s, t, \vec{q}) \, ds \, dt \, d\vec{q} \quad (2.6)$$

We introduced $\vec{q} := (q_1, \dots, q_{N-2})$ for short, and the function L is given by

$$L(q_1, \dots, q_{N-1}) := 2\pi^2 \left(\frac{m(m+2)}{(m+1)^2} \sum_{i=1}^{N-1} q_i^2 + \frac{2m}{(m+1)^2} \sum_{1 \leq i < j \leq N-1} q_i \cdot q_j + \mu \right)^{1/2} \quad (2.7)$$

Note that since $G\xi \notin H^1(\mathbb{R}^{3N})$ for $\xi \neq 0$, the decomposition of u as $u = w + G\xi$ is unique. Moreover, while w depends on μ , ξ is independent of the choice of μ .

Clearly $T_{\text{diag}}(\xi)$ is bounded above and below by $\|\xi\|_{H^{1/2}(\mathbb{R}^{3(N-1)})}^2$, and also $T_{\text{off}}(\xi)$ is bounded in $H^{1/2}(\mathbb{R}^{3(N-1)})$ (see Sect. 3). One readily checks that both $D(F_\alpha)$ and $F_\alpha(u)$ are actually independent of μ for $\mu > 0$, even though $T_{\text{diag}}(\xi)$ and $T_{\text{off}}(\xi)$ depend on μ . The domain $D(F_\alpha)$ is also independent of $\alpha \in \mathbb{R}$. Moreover, under the scaling $u \rightarrow u_\lambda(\cdot) = \lambda^{3N/2} u(\lambda \cdot)$ for $\lambda > 0$, F_α changes as $F_\alpha(u_\lambda) = \lambda^2 F_{\lambda^{-1}\alpha}(u)$. In particular, F_0 is homogeneous of order 2 under scaling.

The quadratic form F_α can be obtained as a limit of a suitably regularized version of (2.1), see [10] and [7, Appendix A]. As we shall see in the next subsection, the parameter α equals $-2\pi^2/a$, where a denotes the scattering length of the pair interaction. We note that other choices for quadratic forms are possible in the unitary case $\alpha = 0$ for small mass m , see [8].

To state our main result, we define, for any $m > 0$,

$$\Lambda(m) = \sup_{s, K \in \mathbb{R}^3, Q > 0} \frac{s^2 + Q^2}{\pi^2(1+m)} \ell_m(s, K, Q)^{-1/2} \int_{\mathbb{R}^3} \frac{1}{t^2} \ell_m(t, K, Q)^{-1/2} \times \frac{|(s+AK) \cdot (t+AK)|}{\left[(s+AK)^2 + (t+AK)^2 + \frac{m}{1+m} (Q^2 + AK^2) \right]^2 - \left[\frac{2}{(1+m)} (s+AK) \cdot (t+AK) \right]^2} dt \quad (2.8)$$

where $A := (2 + m)^{-1}$ and

$$\ell_m(s, K, Q) := \left(\frac{m}{(m + 1)^2} (s + K)^2 + \frac{m}{m + 1} (s^2 + Q^2) \right)^{1/2} \tag{2.9}$$

A somewhat simpler, equivalent expression for $\Lambda(m)$, involving only the supremum over two positive parameters, will be given in Sect. 7. We shall show in Sect. 6 that $\Lambda(m)$ is finite, and satisfies the upper bound

$$\Lambda(m) \leq \frac{4(1 + m)^2(2 + 4m + m^2)^{3/2}}{\sqrt{2\pi} [m(m + 2)]^3} \tag{2.10}$$

Note that (2.10) implies, in particular, that $\lim_{m \rightarrow \infty} \Lambda(m) = 0$.

Our first main result is the following:

Theorem 1. *For any $\xi \in H_{\text{as}}^{1/2}(\mathbb{R}^{3(N-1)})$, $\mu > 0$ and $N \geq 2$,*

$$T_{\text{off}}(\xi) \geq -\Lambda(m) T_{\text{diag}}(\xi) \tag{2.11}$$

In particular, if m is such that $\Lambda(m) < 1$, then F_α is closed and bounded from below by

$$F_\alpha(u) \geq \begin{cases} 0 & \text{for } \alpha \geq 0 \\ -\left(\frac{\alpha}{2\pi^2(1-\Lambda(m))}\right)^2 \|u\|_{L^2(\mathbb{R}^{3N})}^2 & \text{for } \alpha < 0 \end{cases} \tag{2.12}$$

for all $u \in D(F_\alpha)$.

We note that (2.12) follows immediately from (2.11) in combination with the simple estimate $T_{\text{diag}}(\xi) \geq 2\pi^2 \sqrt{\mu} \|\xi\|_{L^2(\mathbb{R}^{3(N-1)})}^2$. For $\alpha < 0$, one simply chooses $\mu = \alpha^2(2\pi^2(1 - \Lambda(m)))^{-2}$, using the independence of $F_\alpha(u)$ of μ . As a closed and bounded from below quadratic form, F_α gives rise to a unique self-adjoint operator [27, Thm. VIII.15] for $\Lambda(m) < 1$. We shall describe it in detail in the next subsection.

The lower bound (2.12) is sharp as $m \rightarrow \infty$. For $\alpha < 0$, $-(\alpha/2\pi^2)^2$ equals the binding energy of the two-particle problem with point interactions. As $m \rightarrow \infty$, only one of the fermions can be bound, hence the ground state energy becomes independent of N in that limit.

We emphasize that in contrast to the previous work [7, 9] we prove a bound on the critical mass that is independent of N and, in particular, does not grow as N gets large. Also the lower bound (2.12) is independent of N .

We shall prove Theorem 1 in Sect. 4 below. The right side of (2.10) turns out to be less than 1 for $m \geq 1.76$, and hence stability holds in that region. For $m = 1$, it equals about 2.47, however, and is larger than 1 as a result of the rather crude bounds leading to (2.10).

In Sect. 7 we evaluate $\Lambda(m)$ numerically and show that it satisfies $\Lambda(1) < 1$. In fact, from the numerics we shall see that $\Lambda(m) < 1$ if $m \geq 0.36$ (see Fig. 1). Recall that F_α is known to be unbounded from below [7, Thm. 2.2] for any $N \geq 2$ for $m \leq 0.0735$. In particular, the critical mass for stability satisfies $0.0735 < m^* < 0.36$.

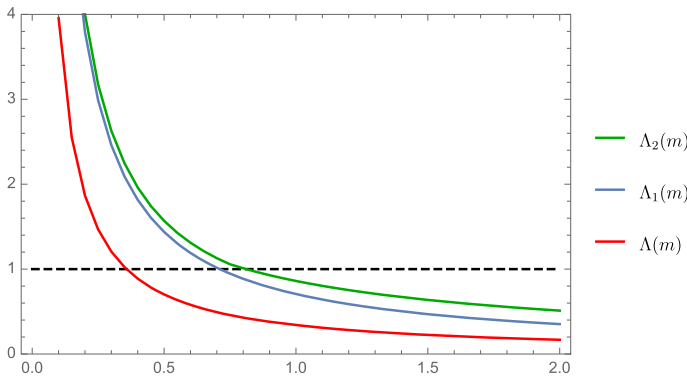


Fig. 1. Numerical evaluation of $\Lambda(m)$ defined in (2.8). In the region $\Lambda(m) < 1$, we prove stability of the system. Asymptotically, $\Lambda(m) \approx 1/(2\sqrt{2}m)$ for large m (and in fact, approximately within a few percent in the whole region $m \gtrsim 1$). For $\Lambda_1(m) < 1$, we prove that the domain of the operator Γ in (2.13) equals $H_{\text{as}}^1(\mathbb{R}^{3(N-1)})$. Moreover, for $\Lambda_2(m) < 1$ the boundary condition in (2.18) implies that for every function in the domain of H_α one has $\xi \in H_{\text{as}}^{3/2}(\mathbb{R}^{3(N-1)})$

2.2. *Hamiltonian.* For $\Lambda(m) < 1$, Theorem 1 implies that

$$T_{\text{diag}}(\xi) + T_{\text{off}}(\xi) = \langle \xi | \Gamma \xi \rangle \tag{2.13}$$

defines a positive selfadjoint operator Γ on $L_{\text{as}}^2(\mathbb{R}^{3(N-1)})$, with domain $D(\Gamma) \subset H_{\text{as}}^{1/2}(\mathbb{R}^{3(N-1)})$. In fact,

$$\Gamma \geq (1 - \Lambda(m)) L \geq (1 - \Lambda(m)) 2\pi^2 \sqrt{\mu} \tag{2.14}$$

where L is short for the multiplication operator in momentum space defined by (2.7).

It is not difficult to see that $H_{\text{as}}^1(\mathbb{R}^{3(N-1)}) \subset D(\Gamma)$ (see Sect. 3), but this inclusion could possibly be strict. In fact, it was shown in [22,24] in the case $N = 2$ that Γ is not selfadjoint on H^1 for certain small m , but admits a one-parameter family of semi-bounded self-adjoint extensions. In contrast, the following theorem implies that $D(\Gamma) = H_{\text{as}}^1(\mathbb{R}^{3(N-1)})$ for larger m , more precisely for $\Lambda_1(m) < 1$, which is slightly more restrictive than our regime of stability, $\Lambda(m) < 1$.

To state our result, we define, analogously to (2.8), for $\beta \geq 0$ and $m > 0$,

$$\begin{aligned} \Lambda_\beta(m) &= \sup_{s, K \in \mathbb{R}^3, Q > 0} \frac{s^2 + Q^2}{\pi^2(1+m)} \int_{\mathbb{R}^3} \frac{1}{t^2} \left(\frac{\ell_m(s, K, Q)^{(\beta-1)/2}}{\ell_m(t, K, Q)^{(\beta+1)/2}} + \frac{\ell_m(t, K, Q)^{(\beta-1)/2}}{\ell_m(s, K, Q)^{(\beta+1)/2}} \right) \\ &\times \frac{|(s + AK) \cdot (t + AK)|}{\left[(s + AK)^2 + (t + AK)^2 + \frac{m}{1+m} (Q^2 + AK^2) \right]^2 - \left[\frac{2}{(1+m)} (s + AK) \cdot (t + AK) \right]^2} dt \end{aligned} \tag{2.15}$$

Note that the integrand in (2.15) is increasing and convex in β , hence $\Lambda_\beta(m)$ is, as a supremum over such functions, also increasing and convex. We have $\Lambda_\beta(m) \geq \Lambda_0(m) = 2\Lambda(m)$. We shall show in Sect. 6 that $\Lambda_\beta(m)$ is finite for $\beta < 3$ and satisfies $\lim_{m \rightarrow \infty} \Lambda_\beta(m) = 0$. In particular, from the convexity it then follows that $\Lambda_\beta(m)$ is continuous in β for $0 \leq \beta < 3$.

Theorem 2. For any $\xi \in H_{\text{as}}^1(\mathbb{R}^{3(N-1)})$, $\mu > 0$ and $N \geq 2$,

$$\|\Gamma\xi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 \geq (1 - \Lambda_1(m)) \|L\xi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 \tag{2.16}$$

In particular, if $\Lambda_1(m) < 1$, then $D(\Gamma) = D(L) = H_{\text{as}}^1(\mathbb{R}^{3(N-1)})$. More generally, for $0 \leq \beta \leq 2$,

$$\|L^{(\beta-1)/2}\Gamma\xi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 \geq (1 - \Lambda_\beta(m)) \|L^{(\beta+1)/2}\xi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 \tag{2.17}$$

for all $\xi \in H_{\text{as}}^{(\beta+1)/2}(\mathbb{R}^{3(N-1)})$.

The proof of Theorem 2 will be given in Sect. 5. A numerical evaluation of $\Lambda_\beta(m)$ yields $\Lambda_1(m) < 1$ for $m \geq 0.72$, while $\Lambda_2(m) < 1$ for $m \geq 0.82$ (see Fig. 1).

In terms of $D(\Gamma)$, the self-adjoint operator H_α defined by the quadratic form F_α in (2.5) can be constructed in a straightforward way following the analogous construction in the two-dimensional case in [10, Sect. 5] (see also [7, 15, 22, 24, 34]). The result is

$$D(H_\alpha) = \left\{ u \in L_{\text{as}}^2(\mathbb{R}^{3N}) \mid u = w + G\xi, w \in H_{\text{as}}^2(\mathbb{R}^{3N}), \xi \in D(\Gamma), \right. \\ \left. w \upharpoonright_{y_N=0} = (2\pi)^{-3/2}(-1)^{N+1}(\alpha + \Gamma)\xi \right\} \tag{2.18}$$

and H_α acts on $u \in D(H_\alpha)$ as

$$(H_\alpha + \mu)u = \left(-\sum_{i=1}^N \Delta_{y_i} - \frac{2}{m+1} \sum_{1 \leq i < j \leq N} \nabla_{y_i} \cdot \nabla_{y_j} + \mu \right) w \tag{2.19}$$

Note that as an H^2 -function, w has an L^2 -restriction to the hyperplane $y_N = 0$, and the last identity in (2.18) has to be understood as an identity of functions in $L_{\text{as}}^2(\mathbb{R}^{3(N-1)})$. In fact, the restriction of the H^2 -function w to the hyperplane $y_N = 0$ is an $H^{1/2}$ function, and hence we conclude that for any $u \in D(H_\alpha)$, the corresponding ξ satisfies $\Gamma\xi \in H^{1/2}$. The last part of Theorem 2 thus implies that for $\Lambda_2(m) < 1$, ξ is necessarily in $H^{3/2}$.

The last identity in (2.18) encodes the boundary condition satisfied by functions $u \in D(H_\alpha)$ at the origin. To see this, consider the behavior of the function $G\xi$ as $y_N \rightarrow 0$ or, equivalently, the integral of (2.4) over q_N in a large ball. A short calculation using (2.4) shows that

$$\lim_{K \rightarrow \infty} \int_{|q_N| < K} \left(\widehat{G\xi}(q_1, \dots, q_N) - \frac{1}{q_N^2}(-1)^{N+1}\widehat{\xi}(q_1, \dots, q_{N-1}) \right) dq_N \\ = \int_{\mathbb{R}^3} \left(G(q_1, \dots, q_N) \sum_{i=1}^{N-1} (-1)^{i+1}\widehat{\xi}(q_1, \dots, q_{i-1}, q_{i+1}, \dots, q_N) \right) dq_N \\ + (-1)^{N+1}\widehat{\xi}(q_1, \dots, q_{N-1}) \lim_{K \rightarrow \infty} \int_{|q_N| < K} \left(G(q_1, \dots, q_N) - \frac{1}{q_N^2} \right) dq_N \\ = (-1)^N \widehat{\Gamma\xi}(q_1, \dots, q_{N-1}) \tag{2.20}$$

where we have used that

$$L(q_1, \dots, q_{N-1}) = - \lim_{K \rightarrow \infty} \int_{|q_N| < K} \left(G(q_1, \dots, q_N) - \frac{1}{q_N^2} \right) dq_N \quad (2.21)$$

We conclude that the boundary condition in (2.18) implies that any $u \in D(H_\alpha)$ has the asymptotic behavior

$$\int_{|q_N| < K} \hat{u}(q_1, \dots, q_N) dq_N \approx (4\pi K + \alpha) (-1)^{N+1} \hat{\xi}(q_1, \dots, q_{N-1}) \quad \text{as } K \rightarrow \infty. \quad (2.22)$$

In particular, u diverges as $2\pi^2/|y_N| + \alpha$ as $|y_N| \rightarrow 0$, and hence α is to be interpreted as $\alpha = -2\pi^2/a$ with a the scattering length of the point interaction. A precise formulation of this divergence in configuration space will be given in Proposition 1 in the next subsection.

As in the case of the corresponding quadratic form, H_α is independent of the parameter μ used in its construction. Under a unitary scaling of the form $U_\lambda \psi(\cdot) = \lambda^{3(N+1)/2} \psi(\lambda \cdot)$, it transforms as $U_\lambda^{-1} H_\alpha U_\lambda = \lambda^2 H_{\lambda^{-1}\alpha}$. Note that in contrast to $D(F_\alpha)$, the domain $D(H_\alpha)$ does depend on α .

2.3. Tan relations. In [31–33], Tan derived a number of identities that should hold for any system of particles with point interactions (see also the review [4] and the references there). These can be experimentally tested, see [16, 25, 26, 29, 36]. In this section, we shall present a rigorous version of the Tan relations for the Hamiltonian H_α constructed in the last subsection. The analysis in this section does not actually use the self-adjointness and analogous results also hold for the general $N + M$ system, irrespective of its stability and the self-adjointness of the corresponding H_α . We shall work with the assumption $\xi \in H^1$, however, which is guaranteed to be the case for $\Lambda_1(m) < 1$, by Theorem 2.

In order to state the results, we have to re-introduce the center-of-mass motion. The Hilbert space for the $N + 1$ system is thus $L^2(\mathbb{R}^3) \otimes L^2_{\text{as}}(\mathbb{R}^{3N})$, and the form domain of the corresponding quadratic form, which we denote by \mathcal{F}_α , equals

$$D(\mathcal{F}_\alpha) = \left\{ \psi = \phi + \mathcal{G}\xi \mid \phi \in H^1(\mathbb{R}^3) \otimes H^1_{\text{as}}(\mathbb{R}^{3N}), \xi \in H^{1/2}(\mathbb{R}^3) \otimes H^{1/2}_{\text{as}}(\mathbb{R}^{3(N-1)}) \right\} \quad (2.23)$$

where

$$\mathcal{G}(k_0, k_1, \dots, k_N) := \left(\frac{1}{2m} k_0^2 + \frac{1}{2} \sum_{i=1}^N k_i^2 + \mu \right)^{-1}, \quad (2.24)$$

$\mathcal{G}\xi$ is short for the function with Fourier transform

$$\begin{aligned} & \widehat{\mathcal{G}\xi}(k_0, k_1, \dots, k_N) \\ &= \mathcal{G}(k_0, k_1, \dots, k_N) \sum_{i=1}^N (-1)^{i+1} \hat{\xi}(k_0 + k_i, k_1, \dots, k_{i-1}, k_{i+1}, \dots, k_N) \end{aligned} \quad (2.25)$$

and, compared to (2.3), we have absorbed a factor $\frac{m+1}{2m}$ into the definition of ξ for simplicity. For $\psi \in D(\mathcal{F}_\alpha)$, we have

$$\begin{aligned} \mathcal{F}_\alpha(\psi) &= \left\langle \phi \left| -\frac{1}{2m} \Delta_{x_0} - \frac{1}{2} \sum_{i=1}^N \Delta_{x_i} + \mu \right| \phi \right\rangle - \mu \|\psi\|_{L^2(\mathbb{R}^{3(N+1)})}^2 \\ &\quad + N \left(\frac{2m}{m+1} \alpha \|\xi\|_{L^2(\mathbb{R}^{3N})}^2 + \mathcal{T}_{\text{diag}}(\xi) + \mathcal{T}_{\text{off}}(\xi) \right) \end{aligned} \tag{2.26}$$

where

$$\begin{aligned} \mathcal{T}_{\text{diag}}(\xi) &:= \int_{\mathbb{R}^{3N}} |\hat{\xi}(k_0, k_1, \vec{k})|^2 \mathcal{L}(k_0, k_1, \vec{k}) \, dk_0 \, dk_1 \, d\vec{k} \\ \mathcal{T}_{\text{off}}(\xi) &:= (N-1) \int_{\mathbb{R}^{3(N+1)}} \hat{\xi}^*(k_0 + s, t, \vec{k}) \hat{\xi}(k_0 + t, s, \vec{k}) \mathcal{G}(k_0, s, t, \vec{k}) \, dk_0 \, ds \, dt \, d\vec{k} \end{aligned} \tag{2.27}$$

and we used $\vec{k} = (k_2, \dots, k_{N-1})$ for short. The function \mathcal{L} is given by

$$\mathcal{L}(k_0, k_1, \dots, k_{N-1}) := 2\pi^2 \left(\frac{2m}{m+1} \right)^{3/2} \left(\frac{k_0^2}{2(m+1)} + \frac{1}{2} \sum_{i=1}^{N-1} k_i^2 + \mu \right)^{1/2} \tag{2.28}$$

Theorem 1 implies that

$$\mathcal{T}_{\text{off}}(\xi) \geq -\Lambda(m) \mathcal{T}_{\text{diag}}(\xi) \quad \text{for all } \xi \in H^{1/2}(\mathbb{R}^3) \otimes H_{\text{as}}^{1/2}(\mathbb{R}^{3(N-1)}). \tag{2.29}$$

To see this, one can either mimic the proof of Theorem 1, or one simply argues as follows. Displaying the dependence on μ explicitly via a superscript in the expressions for $\mathcal{T}_{\text{diag/off}}$ and $\mathcal{T}_{\text{diag/off}}$ in (2.6) and (2.27), respectively, it is straightforward to check that

$$\mathcal{T}_{\text{diag/off}}^\mu(\xi) = \frac{2m}{m+1} \int_{\mathbb{R}^3} T_{\text{diag/off}}^{\tilde{\mu}_P}(\eta_P) \, dP \tag{2.30}$$

where $\tilde{\mu}_P = \frac{2m}{m+1}(\mu + \frac{P^2}{2(m+N)})$ and

$$\hat{\eta}_P(q_1, \dots, q_{N-1}) = \hat{\xi} \left(\frac{m+1}{m+N} P - \sum_{j=1}^{N-1} q_j, q_1 + \frac{1}{m+N} P, \dots, q_{N-1} + \frac{1}{m+N} P \right) \tag{2.31}$$

which is in $H_{\text{as}}^{1/2}(\mathbb{R}^{3(N-1)})$ for almost every $P \in \mathbb{R}^3$. Since the bound (2.11) is uniform in μ , (2.29) follows.

Analogously to the discussion in the previous subsection, for $\Lambda(m) < 1$ the quadratic form $\mathcal{T}_{\text{diag}}(\xi) + \mathcal{T}_{\text{off}}(\xi)$ defines a positive self-adjoint operator $\tilde{\Gamma}$ on $L^2(\mathbb{R}^3) \otimes L_{\text{as}}^2(\mathbb{R}^{3(N-1)})$. Explicitly, $\tilde{\Gamma}$ acts as

$$\begin{aligned} \widehat{\tilde{\Gamma}} \hat{\xi}(k_0, k_1, \dots, k_{N-1}) &= \mathcal{L}(k_0, k_1, \dots, k_{N-1}) \hat{\xi}(k_0, k_1, \dots, k_{N-1}) \\ &\quad + \sum_{j=1}^{N-1} (-1)^{j+1} \int_{\mathbb{R}^3} \mathcal{G}(k_0 - s, s, k_1, \dots, k_{N-1}) \\ &\quad \times \hat{\xi}(k_0 + k_j - s, s, k_1, \dots, k_{j-1}, k_{j+1}, \dots, k_{N-1}) \, ds \end{aligned} \tag{2.32}$$

Theorem 2 implies that the domain $D(\tilde{\Gamma})$ equals $H^1(\mathbb{R}^3) \otimes H_{\text{as}}^1(\mathbb{R}^{3(N-1)})$ in the case $\Lambda_1(m) < 1$. The domain of the self-adjoint operator \mathcal{H}_α corresponding to the quadratic form \mathcal{F}_α is given by those $\psi \in D(\mathcal{F}_\alpha)$ where $\phi \in H^2(\mathbb{R}^3) \otimes H_{\text{as}}^2(\mathbb{R}^{3N})$, $\xi \in D(\tilde{\Gamma})$ and the boundary condition

$$\phi \upharpoonright_{x_N=x_0} = \frac{(-1)^{N+1}}{(2\pi)^{3/2}} \left(\frac{2m\alpha}{m+1} + \tilde{\Gamma} \right) \xi \tag{2.33}$$

is satisfied. The Hamiltonian \mathcal{H}_α acts as

$$(\mathcal{H}_\alpha + \mu) \psi = \left(-\frac{1}{2m} \Delta_{x_0} - \frac{1}{2} \sum_{i=1}^N \Delta_{x_i} + \mu \right) \phi \tag{2.34}$$

It commutes with translations and rotations, and transforms under scaling in the same way as discussed for H_α at the end of the previous subsection.

The connection between the boundary condition (2.33) and the asymptotic behavior of $\psi \in D(\mathcal{H}_\alpha)$ as $|x_N - x_0| \rightarrow 0$ is explored in the following proposition, whose proof will be given in Sect. 8.

Proposition 1. *For any $\psi \in D(\mathcal{H}_\alpha)$ with $\xi \in H^1(\mathbb{R}^{3N})$, we have*

$$\begin{aligned} & \psi \left(R + \frac{r}{1+m}, x_1, \dots, x_{N-1}, R - \frac{mr}{1+m} \right) \\ &= \left(\frac{2\pi^2}{|r|} + \alpha \right) \frac{2m}{m+1} \frac{(-1)^{N+1}}{(2\pi)^{3/2}} \xi(R, x_1, \dots, x_{N-1}) \\ & \quad + v(R, x_1, \dots, x_{N-1}, r) \end{aligned} \tag{2.35}$$

with $v(\cdot, r) \in L^2(\mathbb{R}^{3N})$ for all $r \in \mathbb{R}^3$, and $\lim_{r \rightarrow 0} \|v(\cdot, r)\|_{L^2(\mathbb{R}^{3N})} = 0$.

Proposition 1 immediately implies a two-term asymptotics for the two-particle density

$$\rho(r) = N \int_{\mathbb{R}^{3N}} \left| \psi \left(R + \frac{r}{1+m}, x_1, \dots, x_{N-1}, R - \frac{mr}{1+m} \right) \right|^2 dR dx_1 \cdots dx_{N-1} \tag{2.36}$$

as $r \rightarrow 0$. In fact, ρ satisfies

$$\rho(r) = \frac{\pi}{2} \left(\frac{1}{|r|^2} - \frac{2}{|r|a} \right) \mathcal{C} + g(r) \quad \text{with} \quad \lim_{r \rightarrow 0} |r g(r)| = 0 \tag{2.37}$$

where $a = -2\pi^2/\alpha$ denotes the scattering length and

$$\mathcal{C} = \left(\frac{2m}{m+1} \right)^2 N \|\xi\|_{L^2(\mathbb{R}^{3N})}^2 \tag{2.38}$$

In the physics literature, \mathcal{C} is called the *contact* [31–33]. It turns out to play a crucial role in various other relevant quantities, as we shall demonstrate now.

For general $\psi \in L^2(\mathbb{R}^3) \otimes L_{\text{as}}^2(\mathbb{R}^{3N})$, the momentum densities of the mass m (spin up) particle $n_\uparrow(k)$ and of the mass 1 (spin-down) particles $n_\downarrow(k)$ are defined as

$$\begin{aligned} n_\uparrow(k) &= \int_{\mathbb{R}^{3N}} |\hat{\psi}(k, k_1, \dots, k_N)|^2 dk_1 \cdots dk_N, \\ n_\downarrow(k) &= N \int_{\mathbb{R}^{3N}} |\hat{\psi}(k_0, k, k_2, \dots, k_N)|^2 dk_0 dk_2 \cdots dk_N \end{aligned} \tag{2.39}$$

Our rigorous formulation of the Tan relation for the energy is as follows.

Theorem 3. For $\psi \in D(\mathcal{H}_\alpha)$ with $\xi \in H^1(\mathbb{R}^{3N})$, let \mathcal{C} be given in (2.38), and let

$$p_\uparrow = \frac{2m}{m+1} \|\xi\|_{L^2(\mathbb{R}^{3N})}^{-2} \int_{\mathbb{R}^{3N}} k_1 |\hat{\xi}(k_1, \dots, k_N)|^2 dk_1 \dots dk_N, \quad p_\downarrow = \frac{1}{m} p_\uparrow. \quad (2.40)$$

Then

$$k \mapsto k^2 n_\uparrow(k) - \frac{\mathcal{C}}{|k - p_\uparrow|^2} \in L^1(\mathbb{R}^3) \quad \text{and} \quad k \mapsto k^2 n_\downarrow(k) - \frac{\mathcal{C}}{|k - p_\downarrow|^2} \in L^1(\mathbb{R}^3) \quad (2.41)$$

and we have the identity

$$\begin{aligned} \langle \psi | \mathcal{H}_\alpha \psi \rangle &= \int_{\mathbb{R}^3} \left[\frac{1}{2m} \left(k^2 n_\uparrow(k) - \frac{\mathcal{C}}{|k - p_\uparrow|^2} \right) + \frac{1}{2} \left(k^2 n_\downarrow(k) - \frac{\mathcal{C}}{|k - p_\downarrow|^2} \right) \right] dk \\ &\quad - \frac{m+1}{2m} \mathcal{C} \alpha \end{aligned} \quad (2.42)$$

Since \mathcal{C} , p_\uparrow and p_\downarrow are uniquely determined by the momentum densities via (2.41), Eq. (2.42) expresses the energy solely in terms of the momentum densities. The set of possible momentum densities arising from wave functions $\psi \in D(\mathcal{H}_\alpha)$ is not known, however, and can be expected to depend in a complicated way on both α and N .

The contact \mathcal{C} thus determines the asymptotic behavior of both $n_\uparrow(k)$ and $n_\downarrow(k)$, via $n_\uparrow(k) \approx n_\downarrow(k) \approx \mathcal{C}|k|^{-4}$ for large $|k|$. In fact, up to terms decaying faster than $|k|^{-5}$, we have for large $|k|$

$$n_\uparrow(k) + n_\downarrow(k) \approx \frac{\mathcal{C}}{|k|^2 |k - p_\uparrow|^2} + \frac{\mathcal{C}}{|k|^2 |k - p_\downarrow|^2} \approx \frac{\mathcal{C}}{|k - P|^4} \quad (2.43)$$

for $P = \frac{1}{2}(p_\uparrow + p_\downarrow) = \|\xi\|_{L^2(\mathbb{R}^{3N})}^{-2} \int_{\mathbb{R}^{3N}} k_1 |\hat{\xi}(k_1, \dots, k_N)|^2 dk_1 \dots dk_N$. Note also that due to the fact that $\lim_{K \rightarrow \infty} \int_{|k| < K} (|k|^{-2} - |k - p|^{-2}) dk = 0$ for any $p \in \mathbb{R}^3$, one can rewrite the identity (2.42) as

$$\begin{aligned} \langle \psi | \mathcal{H}_\alpha \psi \rangle &= \lim_{K \rightarrow \infty} \int_{|k| < K} \left[\frac{k^2}{2m} \left(n_\uparrow(k) - \frac{\mathcal{C}}{|k|^4} \right) + \frac{k^2}{2} \left(n_\downarrow(k) - \frac{\mathcal{C}}{|k|^4} \right) \right] dk \\ &\quad - \frac{m+1}{2m} \mathcal{C} \alpha \end{aligned} \quad (2.44)$$

For any stationary state, the contact \mathcal{C} can be computed as the derivative of the energy with respect to α , by the Feynman-Hellmann principle. In fact, for fixed ψ (and hence fixed ξ),

$$\frac{\partial}{\partial \alpha} \mathcal{F}_\alpha(\psi) = \frac{m+1}{2m} \mathcal{C} \quad (2.45)$$

Note that it is important to use the quadratic form formulation here, as the domain of \mathcal{H}_α depends on α and hence ψ cannot be fixed when taking the derivative of $\langle \psi | \mathcal{H}_\alpha \psi \rangle$ with respect to α . Note also the minus sign in front of the last term in (2.42); a naive derivative of (2.42) would give the wrong sign!

The L^1 -property (2.41) claimed in Theorem 3 does not make use of the boundary condition (2.33) satisfied by $\psi \in D(\mathcal{H}_\alpha)$ and holds more generally, in fact. The identity (2.42) only holds for ψ satisfying (2.33), however; i.e., it holds for all functions ψ in the domain of \mathcal{H}_α . (As already mentioned in the beginning of this section, self-adjointness

of \mathcal{H}_α on this domain is not actually needed here. In particular, Theorem 3 holds for all $m > 0$.)

The equations (2.37), (2.41), (2.42) and (2.45) can be interpreted as a rigorous formulation of the Tan relations introduced in [31–33]. There is actually one more relation, a virial type theorem. It is an immediate consequence of the relation $U_\lambda^{-1}\mathcal{H}_\alpha U_\lambda = \lambda^2\mathcal{H}_{\lambda^{-1}\alpha}$ for scaling the variables by $\lambda > 0$ and we shall not discuss it further here.

The proof of Theorem 3 will be given in Sect. 9.

3. Preliminaries

Before giving the proof of the results in the previous section, we collect here a few auxiliary facts that will be used in the proofs.

Lemma 1. *The operator σ on $L^2(\mathbb{R}^3)$ with integral kernel*

$$\sigma(s, t) = (s^2 + 1)^{(\beta-1)/4}(t^2 + 1)^{-(\beta+1)/4} \frac{1}{s^2 + t^2 + \lambda s \cdot t + 1} \tag{3.1}$$

is bounded for $-2 < \lambda < 2$ and $-2 < \beta < 2$.

Proof. We use the Schur test in the form

$$\|\sigma\| \leq \frac{1}{2} \sup_s h(s) \int_{\mathbb{R}^3} h(t)^{-1} (|\sigma(s, t)| + |\sigma(t, s)|) dt \tag{3.2}$$

for any positive function h , which is a consequence of the Cauchy-Schwarz inequality. Since $|\lambda| < 2$, a pointwise estimate of the kernel reduces the problem to the case $\lambda = 0$. Choosing $h(t) = (t^2 + 1)^\gamma$ one easily checks that the right side of (3.2) is finite if and only if $(1 + |\beta|)/4 < \gamma < (5 - |\beta|)/4$. \square

In the special case $\beta = 0$, Lemma 1 can be used to show that, for some $c > 0$, $|T_{\text{off}}(\xi)| \leq c(N - 1)T_{\text{diag}}(\xi)$ for all $\xi \in H_{\text{as}}^{1/2}(\mathbb{R}^{3(N-1)})$. In particular, F_α is well-defined on its domain (2.3). Similarly, $\|L^{(\beta-1)/2}\Gamma\xi\|_{L^2(\mathbb{R}^{3(N-1)})}$ is finite for $\xi \in H_{\text{as}}^{(\beta+1)/2}(\mathbb{R}^{3(N-1)})$ for $0 \leq \beta < 2$. For $\beta = 1$, this implies that the domain of Γ contains $H_{\text{as}}^1(\mathbb{R}^{3(N-1)})$.

Lemma 2. *The operator σ on $L^2(\mathbb{R}^3)$ with integral kernel*

$$\sigma(s, t) = \left(\frac{(s^2 + \nu)^{(\beta-1)/4}}{(t^2 + \nu)^{(\beta+1)/4}} + \frac{(t^2 + \nu)^{(\beta-1)/4}}{(s^2 + \nu)^{(\beta+1)/4}} \right) \frac{1}{s^2 + t^2 + \lambda s \cdot t + 1} \tag{3.3}$$

is bounded and non-negative for $-2 < \beta < 2$, $\nu \geq 1/2$ and $-2 < \lambda \leq 0$.

Proof. Boundedness follows immediately from Lemma 1. For $\beta = 0$, positivity can be deduced from the integral representation

$$\left(t^2 + s^2 + \lambda s \cdot t + 1 \right)^{-1} = \int_0^\infty e^{-r(1+\lambda/2)t^2} e^{-r(1+\lambda/2)s^2} e^{r\lambda(t-s)^2/2} e^{-r} dr, \tag{3.4}$$

noting that $-2 < \lambda \leq 0$ and that the Gaussian has a positive Fourier transform. We are thus left with proving positivity for $\beta \neq 0$. Without loss of generality, we may assume $\beta > 0$, since σ is invariant under the transformation $\beta \rightarrow -\beta$. To this aim, we use

$$x^{-\beta/2} = c_\beta \int_0^\infty \frac{1}{x+r} r^{-\beta/2} dr \tag{3.5}$$

with $c_\beta = \pi^{-1} \sin(\frac{\pi}{2}\beta)$ for $x > 0$ and $0 < \beta < 2$ to rewrite the kernel as

$$\begin{aligned} \sigma(s, t) &= c_\beta (s^2 + v)^{(\beta-1)/4} (t^2 + v)^{(\beta-1)/4} \\ &\times \int_0^\infty \left(\frac{1}{s^2 + v + r} + \frac{1}{t^2 + v + r} \right) \frac{r^{-\beta/2}}{s^2 + t^2 + \lambda s \cdot t + 1} dr \end{aligned} \tag{3.6}$$

Let us rewrite the integrand further as

$$\begin{aligned} &r^{-\beta/2} \frac{1}{s^2 + v + r} \frac{1}{t^2 + v + r} \frac{s^2 + t^2 + 2(v+r)}{s^2 + t^2 + \lambda s \cdot t + 1} \\ &= r^{-\beta/2} \frac{1}{s^2 + v + r} \frac{1}{t^2 + v + r} \left(1 + \frac{2(v+r) - 1 - \lambda s \cdot t}{s^2 + t^2 + \lambda s \cdot t + 1} \right) \end{aligned} \tag{3.7}$$

Using again (3.4), as well as $2(v+r) \geq 1$ and $\lambda \leq 0$, we see that (3.7) defines a non-negative operator. This completes the proof. \square

Lemma 3. Consider the bounded operator σ on $L^2(\mathbb{R}^3)$ with integral kernel given by (3.3) for $-2 < \beta < 2$, $v \geq 1/2$ and $0 \leq \lambda < 2$. Its positive and negative parts are the operators with kernels

$$\begin{aligned} \sigma_+(s, t) &= \frac{1}{2} (\sigma(s, t) + \sigma(s, -t)) \\ \sigma_-(s, t) &= -\frac{1}{2} (\sigma(s, t) - \sigma(s, -t)) \end{aligned} \tag{3.8}$$

respectively.

Proof. Let R denote the reflection operator $(R\varphi)(s) = \varphi(-s)$ for $\varphi \in L^2(\mathbb{R}^3)$. The operators R and σ clearly commute. Moreover, the product σR equals the operator with integral kernel (3.3) and λ replaced by $-\lambda$, which was shown to be non-negative in Lemma 2. One readily checks that this implies that the positive and negative parts of σ are given by

$$\sigma_\pm = \pm \frac{1}{2} \sigma (1 \pm R), \tag{3.9}$$

respectively. In fact, clearly $\sigma_+ \sigma_- = \sigma_- \sigma_+ = 0$, and $\sigma_\pm = \frac{1}{2} \sigma R(1 \pm R)$, which is a product of two commuting nonnegative operators. \square

4. Proof of Theorem 1

We assume $N \geq 3$ and define, for fixed $\vec{q} \in \mathbb{R}^{3(N-2)}$ and $-2 < \beta < 2$, an operator τ^β on $L^2(\mathbb{R}^3)$ via the quadratic form

$$\langle \varphi | \tau^\beta | \varphi \rangle = \frac{1}{2} \int_{\mathbb{R}^6} \varphi^*(s) \varphi(t) \left(\frac{L(s, \vec{q})^{(\beta-1)/2}}{L(t, \vec{q})^{(\beta+1)/2}} + \frac{L(t, \vec{q})^{(\beta-1)/2}}{L(s, \vec{q})^{(\beta+1)/2}} \right) G(s, t, \vec{q}) \, ds \, dt \tag{4.1}$$

where L and G are defined in (2.7) and (2.2), respectively. Let $K := \sum_{i=1}^{N-2} q_i$, and recall that $A = 1/(m + 2)$. The following observation is key to our further investigation. We shall need it here for $\beta = 0$ only, but state it more generally for later use in the proof of Theorem 2.

Lemma 4. *The operator τ^β defined in (4.1) is bounded on $L^2(\mathbb{R}^3)$. Its positive and negative parts, τ_{\pm}^β , are the operators with integral kernels*

$$\begin{aligned} \tau_+^\beta(s, t; \vec{q}) &= \frac{1}{4} \left(\frac{L(s, \vec{q})^{(\beta-1)/2}}{L(t, \vec{q})^{(\beta+1)/2}} + \frac{L(t, \vec{q})^{(\beta-1)/2}}{L(s, \vec{q})^{(\beta+1)/2}} \right) (G(s, t, \vec{q}) + G(s, -t - 2AK, \vec{q})) \\ \tau_-^\beta(s, t; \vec{q}) &= -\frac{1}{4} \left(\frac{L(s, \vec{q})^{(\beta-1)/2}}{L(t, \vec{q})^{(\beta+1)/2}} + \frac{L(t, \vec{q})^{(\beta-1)/2}}{L(s, \vec{q})^{(\beta+1)/2}} \right) (G(s, t, \vec{q}) - G(s, -t - 2AK, \vec{q})) \end{aligned} \tag{4.2}$$

respectively.

Proof. Let $Q^2 := \sum_{i=1}^{N-2} q_i^2$, and define $\lambda := 2/(m + 1)$. A simple calculation shows that

$$G(s - AK, t - AK, \vec{q})^{-1} = t^2 + s^2 + \lambda s \cdot t + C \tag{4.3}$$

where

$$C = C(\vec{q}) = \frac{m}{m + 1} (AK^2 + Q^2) + \mu \tag{4.4}$$

Similarly,

$$L(s - AK, \vec{q}) = 2\pi^2 \left(\frac{m(m + 2)}{(m + 1)^2} s^2 + C \right)^{1/2} \tag{4.5}$$

In particular, after a unitary translation by AK , the operator τ^β becomes the operator σ with integral kernel

$$\begin{aligned} \sigma(s, t) &= \frac{m + 1}{4\pi^2} \left(\frac{[m(m + 2)s^2 + (m + 1)^2C]^{(\beta-1)/4}}{[m(m + 2)t^2 + (m + 1)^2C]^{(\beta+1)/4}} \right. \\ &\quad \left. + \frac{[m(m + 2)t^2 + (m + 1)^2C]^{(\beta-1)/4}}{[m(m + 2)s^2 + (m + 1)^2C]^{(\beta+1)/4}} \right) \\ &\quad \times (t^2 + s^2 + \lambda s \cdot t + C)^{-1} \end{aligned} \tag{4.6}$$

After a simple rescaling of the variables by \sqrt{C} , this is exactly of the form (3.3), with $v = (m + 1)^2/(m(m + 2)) > 1/2$ (in fact, > 1). Hence boundedness of σ follows from

Lemma 1. Moreover, Lemma 3 applies, which states that the positive and negative parts of σ are given by

$$\sigma_{\pm} = \pm \frac{1}{2} \sigma (1 \pm R), \tag{4.7}$$

where R denotes reflection. Undoing the unitary translation by AK , this leads to the statement of the lemma. \square

For $\xi \in H_{\text{as}}^{1/2}(\mathbb{R}^{3(N-1)})$, we define $\varphi \in L^2_{\text{as}}(\mathbb{R}^{3(N-1)})$ by $\varphi(s, \vec{q}) = L(s, \vec{q})^{1/2} \hat{\xi}(s, \vec{q})$. Then $T_{\text{diag}}(\xi) = \|\varphi\|_{L^2(\mathbb{R}^{3(N-1)})}^2$, and

$$\begin{aligned} T_{\text{off}}(\xi) &= (N-1) \int_{\mathbb{R}^{3N}} \varphi^*(s, \vec{q}) \varphi(t, \vec{q}) L(s, \vec{q})^{-1/2} L(t, \vec{q})^{-1/2} G(s, t, \vec{q}) \, ds \, dt \, d\vec{q} \\ &\geq -(N-1) \int_{\mathbb{R}^{3N}} \varphi^*(s, \vec{q}) \varphi(t, \vec{q}) \tau_-^0(s, t; \vec{q}) \, ds \, dt \, d\vec{q} \end{aligned} \tag{4.8}$$

where we simply dropped the positive part of the operator τ^0 appearing on the right side. Its negative part, τ_-^0 , is explicitly identified in Lemma 4. To proceed, we use the fact that φ is antisymmetric. We introduce

$$\tilde{\tau}_-(s, \vec{q}, t, \vec{\ell}) = \tau_-^0(s, t; \vec{q}) \delta(\vec{q} - \vec{\ell}) \tag{4.9}$$

for $\vec{\ell} \in \mathbb{R}^{3(N-2)}$, and rewrite the term on the right side of (4.8) as

$$\begin{aligned} &(N-1) \int_{\mathbb{R}^{3N}} \varphi^*(s, \vec{q}) \varphi(t, \vec{q}) \tau_-^0(s, t; \vec{q}) \, ds \, dt \, d\vec{q} \\ &= \sum_{i=0}^{N-2} \int_{\mathbb{R}^{6(N-1)}} \varphi^*(s, \vec{q}) \varphi(t, \vec{\ell}) \tilde{\tau}_-(q_i, \hat{q}_i, \ell_i, \hat{\ell}_i) \, ds \, dt \, d\vec{q} \, d\vec{\ell} \end{aligned} \tag{4.10}$$

where $\hat{q}_i = (q_1, \dots, q_{i-1}, s, q_{i+1}, \dots, q_{N-2})$ and $\hat{\ell}_i = (\ell_1, \dots, \ell_{i-1}, t, \ell_{i+1}, \dots, \ell_{N-2})$ for $1 \leq i \leq N-2$, as well as $q_0 = s, \hat{q}_0 = \vec{q}, \ell_0 = t, \hat{\ell}_0 = \vec{\ell}$. To bound this last expression, we use the Schwarz inequality, as in (3.2), to obtain

$$(4.10) \leq \|\varphi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 \sup_{s, \vec{q}} h(s, \vec{q}) \sum_{i=0}^{N-2} \int_{\mathbb{R}^{3(N-1)}} h(t, \vec{\ell})^{-1} |\tilde{\tau}_-(q_i, \hat{q}_i, \ell_i, \hat{\ell}_i)| \, dt \, d\vec{\ell} \tag{4.11}$$

for any positive function h . Assume that h is symmetric with respect to permutations. Inserting the special structure (4.9), the expression on the right side of (4.11) then equals

$$\|\varphi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 \sup_{s, \vec{q}} h(s, \vec{q}) \sum_{i=0}^{N-2} \int_{\mathbb{R}^3} h(t, \hat{q}_i)^{-1} |\tau_-^0(q_i, t; \hat{q}_i)| \, dt \tag{4.12}$$

We shall choose $h(s, \vec{q}) = s^2 \prod_{j=1}^{N-2} q_j^2$ in (4.12). The resulting bound is then

$$\begin{aligned}
 (4.10) &\leq \|\varphi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 \sup_{s, \vec{q}} \sum_{i=0}^{N-2} \int_{\mathbb{R}^3} \frac{q_i^2}{t^2} |\tau_-^0(q_i, t; \hat{q}_i)| dt \\
 &\leq \|\varphi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 \sup_{s, \vec{q}} \left(s^2 + Q^2\right) \max_{0 \leq i \leq N-2} \int_{\mathbb{R}^3} \frac{1}{t^2} |\tau_-^0(q_i, t; \hat{q}_i)| dt \quad (4.13)
 \end{aligned}$$

where we again use the notation $Q^2 = \sum_{i=1}^{N-2} q_i^2$, as in the proof of Lemma 4. Since for any $1 \leq i \leq N - 2$, $s^2 + Q^2$ is symmetric under exchange of s and q_i , we can drop the maximum over i when taking the supremum over s and \vec{q} , and simply take $i = 0$ (or any other value of i , in fact). We thus arrive at

$$(4.10) \leq \|\varphi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 \sup_{s, \vec{q}} \left(s^2 + Q^2\right) \int_{\mathbb{R}^3} \frac{1}{t^2} |\tau_-^0(s, t; \vec{q})| dt \quad (4.14)$$

To complete the proof of (2.11), we need to show that the term multiplying $\|\varphi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 = T_{\text{diag}}(\xi)$ on the right side of (4.14) is bounded by $\Lambda(m)$. Recall the explicit expression of $\tau_-^0(s, t; \vec{q})$, given in (4.2) above. We have

$$\begin{aligned}
 |\tau_-^0(s, t; \vec{q})| &= \frac{1}{\pi^2(1+m)} \left(\frac{m}{(m+1)^2} (s+K)^2 + \frac{m}{m+1} (s^2 + Q^2) + \mu \right)^{-1/4} \\
 &\times \left(\frac{m}{(m+1)^2} (t+K)^2 + \frac{m}{m+1} (t^2 + Q^2) + \mu \right)^{-1/4} \\
 &\times \frac{|(s+AK) \cdot (t+AK)|}{\left[(s+AK)^2 + (t+AK)^2 + \frac{m}{1+m} (Q^2 + AK^2) + \mu \right]^2 - \left[\frac{2}{(1+m)} (s+AK) \cdot (t+AK) \right]^2} \quad (4.15)
 \end{aligned}$$

For an upper bound, we can replace μ by 0. Moreover, we can replace the supremum over $\vec{q} \in \mathbb{R}^{3(N-2)}$ by a supremum over all $Q > 0$ and $K \in \mathbb{R}^3$. This yields (2.11).

To complete the proof of Theorem 1, we have to show that F_α is closed for $\Lambda(m) < 1$. This was already proved in [7, Thm. 2.1], we include the proof here for completeness. Given a sequence $u_n \in D(F_\alpha)$ with $\|u_n - u_m\|_{L^2(\mathbb{R}^{3N})} \rightarrow 0$ and $F_\alpha(u_n - u_m) \rightarrow 0$ as $n, m \rightarrow \infty$, we need to show that there exists a $u \in D(F_\alpha)$ with $\lim_{n \rightarrow \infty} \|u_n - u\|_{L^2(\mathbb{R}^{3N})} = 0$ and $\lim_{n \rightarrow \infty} F_\alpha(u_n - u) = 0$. We choose any $\mu > 0$ for $\alpha \geq 0$, and $\mu > \alpha^2(2\pi(1 - \Lambda(m))^{-2})$ for $\alpha < 0$. For such a choice, writing $u_n = w_n + G\xi_n$, the bound (2.11) implies that $\|w_n - w_m\|_{H^1(\mathbb{R}^{3N})} \rightarrow 0$ and $\|\xi_n - \xi_m\|_{H^{1/2}(\mathbb{R}^{3(N-1)})} \rightarrow 0$ as $n, m \rightarrow \infty$, and hence $w_n \rightarrow w$ and $\xi_n \rightarrow \xi$ for some w and ξ , respectively, in the corresponding norms. Since $\|G(\xi_n - \xi_m)\|_{L^2(\mathbb{R}^{3N})} \leq \text{const} \|\xi_n - \xi_m\|_{L^2(\mathbb{R}^{3(N-1)})}$, u_n converges to $u = w + G\xi$ in $L^2(\mathbb{R}^{3N})$. Moreover, since $|F_\alpha(u_n - u)|$ is bounded from above by $\text{const} (\|w_n - w\|_{H^1(\mathbb{R}^{3N})}^2 + \|\xi_n - \xi\|_{H^{1/2}(\mathbb{R}^{3(N-1)})}^2)$ (compare with the remark after Lemma 1 in Sect. 3), the result follows. \square

Remark 1. It is worth pointing out that the antisymmetry of the wave functions enters our proof of stability in three different ways. The first two concern the very definition of the model. First, there are no point interactions among the N particles of mass 1 themselves, due to the antisymmetry which forces the wave functions to vanish at particle coincidences. Second, the term T_{off} in the definition (2.5) of the quadratic form F_α enters with a plus sign, while it would have a minus sign for bosons. This fact is crucial, as it allows to work with the negative part of the operator τ^0 in (4.1) instead of the positive

part, which is larger. And third, we use the symmetry to replace the factor $(N - 1)$ by a sum over particles in (4.10).

This last step would also work for bosons, only the symmetry of the absolute value of the wave functions is important. For the first two points, however, the antisymmetry is crucial. In the bosonic case, there is instability for any $N \geq 2$ and any $0 < m < \infty$ [5, 30, 39] (a fact known as the Thomas effect [35]). While T_{off} can be bounded from below by $-T_{\text{diag}}$, as Theorem 1 shows, it is in fact known that $T_{\text{off}}(\xi) \leq T_{\text{diag}}(\xi)$ is false for suitable ξ for any m [7].

5. Proof of Theorem 2

Let us define the operator J by $\Gamma = L + J$, i.e., $T_{\text{off}}(\xi) = \langle \xi | J \xi \rangle$ for $\xi \in H_{\text{as}}^1(\mathbb{R}^{3(N-1)})$. For $0 \leq \beta < 2$, we have

$$\begin{aligned} \|L^{(\beta-1)/2} \Gamma \xi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 &= \|L^{(\beta+1)/2} \xi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 \\ &\quad + \langle \xi | (JL^\beta + L^\beta J) \xi \rangle + \|L^{(\beta-1)/2} J \xi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 \\ &\geq \|L^{(\beta+1)/2} \xi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 + \langle \xi | (JL^\beta + L^\beta J) \xi \rangle \end{aligned} \tag{5.1}$$

for all $\xi \in H_{\text{as}}^{(\beta+1)/2}(\mathbb{R}^{3(N-1)})$. The result (2.17) thus follows if we can show that

$$\langle \xi | (JL^\beta + L^\beta J) \xi \rangle \geq -\Lambda_\beta(m) \|L^{(\beta+1)/2} \xi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 \tag{5.2}$$

With $\varphi = L^{(\beta+1)/2} \xi$ this reads, equivalently,

$$\langle \varphi | (L^{-(\beta+1)/2} J L^{(\beta-1)/2} + L^{(\beta-1)/2} J L^{-(\beta+1)/2}) \varphi \rangle \geq -\Lambda_\beta(m) \|\varphi\|_{L^2(\mathbb{R}^{3(N-1)})}^2 \tag{5.3}$$

for all $\varphi \in L_{\text{as}}^2(\mathbb{R}^{3(N-1)})$. The left side equals

$$(N - 1) \int_{\mathbb{R}^{3N}} \hat{\varphi}^*(s, \vec{q}) \hat{\varphi}(t, \vec{q}) \left(\frac{L(t, \vec{q})^{(\beta-1)/2}}{L(s, \vec{q})^{(\beta+1)/2}} + \frac{L(s, \vec{q})^{(\beta-1)/2}}{L(t, \vec{q})^{(\beta+1)/2}} \right) G(s, t, \vec{q}) \, ds \, dt \, d\vec{q} \tag{5.4}$$

where $\vec{q} \in \mathbb{R}^{3(N-2)}$ and L and G are defined in (2.7) and (2.2), respectively.

The above integral over s and t , for fixed \vec{q} , is the expectation of (twice) the operator τ^β defined in (4.1). Lemma 4 identifies its negative and positive parts. Dropping the latter, we thus have

$$\begin{aligned} (5.4) &\geq (N - 1) \int_{\mathbb{R}^{3N}} \hat{\varphi}^*(s, \vec{q}) \hat{\varphi}(t, \vec{q}) \left(\frac{L(t, \vec{q})^{(\beta-1)/2}}{L(s, \vec{q})^{(\beta+1)/2}} + \frac{L(s, \vec{q})^{(\beta-1)/2}}{L(t, \vec{q})^{(\beta+1)/2}} \right) \\ &\quad \times \frac{1}{2} (G(s, t, \vec{q}) - G(s, -t - 2AK, \vec{q})) \, ds \, dt \, d\vec{q} \end{aligned} \tag{5.5}$$

The remainder of the proof proceeds in exactly the same way as in the proof of Theorem 1, Eqs. (4.9)–(4.14), and we shall not repeat it here. The result is (2.17), for any $0 \leq \beta < 2$. The limiting case $\beta = 2$ is then obtained by monotone convergence, using that $\Lambda_\beta(m)$ is convex and thus continuous in β . (Note that for $\beta = 2$, the left side of (2.17) need not be finite, a priori.) \square

6. Upper Bound on $\Lambda_\beta(m)$

In this section we shall prove an upper bound on $\Lambda_\beta(m)$. While only the case $0 \leq \beta \leq 2$ is of interest here, our bound is actually valid for all $0 \leq \beta < 3$. We start with proving the bound (2.10) on $\Lambda(m)$. Recall the definitions of $\Lambda(m)$ and ℓ_m in (2.8) and (2.9), respectively, as well as $A = (2 + m)^{-1}$. We shall use that

$$\ell_m(s, K, Q) \geq \frac{\sqrt{m(m+2)}}{m+1} |s + AK| \tag{6.1}$$

and that

$$\begin{aligned} & \left[(s + AK)^2 + (t + AK)^2 + \frac{m}{1+m} (Q^2 + AK^2) \right]^2 - \left[\frac{2}{(1+m)} (s + AK) \cdot (t + AK) \right]^2 \\ & \geq \frac{m(m+2)}{(1+m)^2} \left[(s + AK)^2 + (t + AK)^2 + \frac{m}{1+m} (Q^2 + AK^2) \right]^2 \\ & \geq \frac{m(m+2)}{(1+m)^2} \left[\frac{m(2+m)}{2+4m+m^2} (s^2 + t^2) + \frac{m}{1+m} Q^2 \right]^2 \end{aligned} \tag{6.2}$$

Together with the simple bound

$$|s + AK|^{1/2} |t + AK|^{1/2} \leq \sqrt{\frac{1}{2} (s + AK)^2 + \frac{1}{2} (t + AK)^2} \tag{6.3}$$

this gives

$$\begin{aligned} \Lambda(m) & \leq \frac{(1+m)^2}{\sqrt{2}\pi^2 [m(m+2)]^{3/2}} \sup_{s \in \mathbb{R}^3, Q > 0} \int_{\mathbb{R}^3} \frac{1}{t^2} \frac{s^2 + Q^2}{\left[\frac{m(2+m)}{2+4m+m^2} (s^2 + t^2) + \frac{m}{1+m} Q^2 \right]^{3/2}} dt \\ & = \frac{4(1+m)^2 (2+4m+m^2)^{3/2}}{\sqrt{2}\pi [m(m+2)]^3} \sup_{s \in \mathbb{R}^3, Q > 0} \frac{s^2 + Q^2}{s^2 + \frac{2+4m+m^2}{(2+m)(1+m)} Q^2} \end{aligned} \tag{6.4}$$

Since $2 + 4m + m^2 > (2 + m)(1 + m)$, the last supremum equals 1, and we obtain the bound (2.10).

The same strategy can be used to derive an upper bound on $\Lambda_\beta(m)$ in (2.15), for $\beta \leq 1$. Instead of (6.3), one uses

$$\begin{aligned} & |s + AK|^{(1+\beta)/2} |t + AK|^{(1-\beta)/2} + |s + AK|^{(1-\beta)/2} |t + AK|^{(1+\beta)/2} \\ & \leq \sqrt{2(s + AK)^2 + 2(t + AK)^2} \end{aligned} \tag{6.5}$$

(which follows from convexity of the exponential function, $xy \leq \frac{1}{p}x^p + \frac{1}{q}y^q$ for $x, y \geq 0$, $p > 1$, $\frac{1}{p} + \frac{1}{q} = 1$), resulting in

$$\Lambda_\beta(m) \leq \frac{4\sqrt{2}(1+m)^2(2+4m+m^2)^{3/2}}{\pi [m(m+2)]^3} \quad \text{for } \beta \leq 1. \tag{6.6}$$

For $1 < \beta < 3$, we need an upper bound on ℓ_m , and we shall simply use

$$\ell_m(s, K, Q) \leq \sqrt{(s + AK)^2 + \frac{m}{m+1} (Q^2 + AK^2)} \tag{6.7}$$

For a lower bound, we shall use (6.1) for one power of ℓ_m , and

$$\ell_m(s, K, Q) \geq \sqrt{\frac{m}{m+1}(s^2 + Q^2)} \tag{6.8}$$

for the remaining $\ell_m^{(\beta-1)/2}$. This leads to

$$\begin{aligned} \Lambda_\beta(m) &\leq \frac{1}{\pi^2} \frac{(m+1)^{(\beta+7)/4}}{m^{(\beta+5)/4}(2+m)^{3/2}} \sup_{s \in \mathbb{R}^3, Q > 0} \int_{\mathbb{R}^3} \frac{1}{t^2} \left(\frac{1}{|t|^{(\beta-1)/2}} + \frac{1}{(s^2 + Q^2)^{(\beta-1)/4}} \right) \\ &\quad \times \frac{s^2 + Q^2}{\left[\frac{m(2+m)}{2+4m+m^2}(s^2 + t^2) + \frac{m}{1+m}Q^2 \right]^{(7-\beta)/4}} dt \\ &= \frac{4}{\pi} \frac{(m+1)^{(\beta+7)/4}}{m^3(2+m)^{(13-\beta)/4}} (2 + 4m + m^2)^{(7-\beta)/4} \left(\frac{2}{3-\beta} + \frac{\sqrt{\pi}}{2} \frac{\Gamma((5-\beta)/4)}{\Gamma((7-\beta)/4)} \right) \end{aligned} \tag{6.9}$$

for $1 < \beta < 3$, where Γ denotes the gamma-function in the last expression. In particular, $\Lambda_\beta(m)$ is finite for $\beta < 3$, and decays at least like m^{-1} for large m .

7. Numerical Evaluation of $\Lambda_\beta(m)$

Recall the definition of $\Lambda(m)$ in (2.8). In order to obtain a numerical value for $\Lambda(m)$, it is convenient to simplify this expression a bit. As a first step, we claim that, given s , the supremum over K in (2.8) is attained at some K of the form $K = -bs$ for $0 \leq b \leq 1/A = 2 + m$. To see this, we substitute $\tilde{s} = s + AK$, $\tilde{t} = t + AK$, and rewrite (2.8) as

$$\begin{aligned} \Lambda(m) &= \sup_{\tilde{s}, K \in \mathbb{R}^3, Q > 0} \frac{(\tilde{s} - AK)^2 + Q^2}{\pi^2(1+m)} \left(\frac{m(m+2)}{(m+1)^2} \tilde{s}^2 + \frac{m}{m+1}(Q^2 + AK^2) \right)^{-1/4} \\ &\quad \times \int_{\mathbb{R}^3} \frac{1}{(\tilde{t} - AK)^2} \left(\frac{m(m+2)}{(m+1)^2} \tilde{t}^2 + \frac{m}{m+1}(Q^2 + AK^2) \right)^{-1/4} \\ &\quad \times \frac{|\tilde{s} \cdot \tilde{t}|}{\left[\tilde{s}^2 + \tilde{t}^2 + \frac{m}{1+m}(Q^2 + AK^2) \right]^2 - \left[\frac{2}{(1+m)} \tilde{s} \cdot \tilde{t} \right]^2} d\tilde{t} \end{aligned} \tag{7.1}$$

Since the term on the last line is invariant under the reflection $\tilde{t} \mapsto -\tilde{t}$, the integral above is equal to

$$\begin{aligned} &\int_{\mathbb{R}^3} \frac{\tilde{t}^2 + A^2K^2}{(\tilde{t}^2 + A^2K^2)^2 - 4A^2(\tilde{t} \cdot K)^2} \left(\frac{m(m+2)}{(m+1)^2} \tilde{t}^2 + \frac{m}{m+1}(Q^2 + AK^2) \right)^{-1/4} \\ &\quad \times \frac{|\tilde{s} \cdot \tilde{t}|}{\left[\tilde{s}^2 + \tilde{t}^2 + \frac{m}{1+m}(Q^2 + AK^2) \right]^2 - \left[\frac{2}{(1+m)} \tilde{s} \cdot \tilde{t} \right]^2} d\tilde{t} \end{aligned} \tag{7.2}$$

When optimizing over the orientation of \tilde{s} and K , the very first factor after the supremum in (7.1) is clearly largest if \tilde{s} and K are antiparallel. That the same is true for the integral (7.2) is the content of the following lemma, whose proof is an easy exercise.

Lemma 5. *Let f and g be measurable functions on $[-1, 1]$ that are non-negative, even, and increasing on $[0, 1]$. For $a, b \in \mathbb{S}^2$,*

$$\int_{\mathbb{S}^2} f(\omega \cdot a)g(\omega \cdot b) \, d\omega \tag{7.3}$$

is largest if a and b are either parallel or antiparallel (as vectors in \mathbb{R}^3).

Proof. We can represent the functions f and g by their level sets, and write

$$(7.3) = \int_{\mathbb{S}^2 \times \mathbb{R}_+^3} \chi_{\{f>x\}}(\omega \cdot a)\chi_{\{g>y\}}(\omega \cdot b) \, d\omega \, dx \, dy \tag{7.4}$$

The support of the function $\omega \mapsto \chi_{\{f>x\}}(\omega \cdot a)$ consists of the union of two spherical caps, centered at $\pm a$, respectively, and similarly for $\chi_{\{g>y\}}(\omega \cdot b)$. If $\pm a$ is parallel to b , the integral over \mathbb{S}^2 in (7.4) (for fixed x and y) is clearly largest, since one of the characteristic functions simply equals 1 on the support of the other in this case. This completes the proof. \square

The angular part of the integral in (7.2) is exactly of the form (7.3). We thus conclude that we can restrict the supremum in (7.1) to the set where $K = -\kappa\tilde{s}$ for some $\kappa \geq 0$ or, equivalently, $K = -bs$ for some $0 \leq b = \kappa/(1 + \kappa A) \leq 1/A$.

To evaluate $\Lambda(m)$, we thus have to find the supremum over $\tilde{s} \in \mathbb{R}^3, \kappa \geq 0$ and $Q \geq 0$ of

$$\begin{aligned} & \frac{\tilde{s}^2(1 + \kappa A)^2 + Q^2}{\pi^2(1 + m)} \left(\frac{m(m + 2)}{(m + 1)^2} \tilde{s}^2 + \frac{m}{m + 1} (Q^2 + A\kappa^2\tilde{s}^2) \right)^{-1/4} \\ & \times \int_{\mathbb{R}^3} \frac{\tilde{t}^2 + A^2\kappa^2\tilde{s}^2}{(\tilde{t}^2 + A^2\kappa^2\tilde{s}^2)^2 - 4A^2\kappa^2(\tilde{t} \cdot \tilde{s})^2} \left(\frac{m(m + 2)}{(m + 1)^2} \tilde{t}^2 + \frac{m}{m + 1} (Q^2 + A\kappa^2\tilde{s}^2) \right)^{-1/4} \\ & \times \frac{|\tilde{s} \cdot \tilde{t}|}{[\tilde{s}^2 + \tilde{t}^2 + \frac{m}{1+m} (Q^2 + A\kappa^2\tilde{s}^2)]^2 - [\frac{2}{(1+m)} \tilde{s} \cdot \tilde{t}]^2} \, d\tilde{t} \end{aligned} \tag{7.5}$$

After carrying out the angle integration, this becomes

$$\begin{aligned} & 2 \frac{\tilde{s}^2(1 + \kappa A)^2 + Q^2}{\pi(1 + m)} \left(\frac{m(m + 2)}{(m + 1)^2} \tilde{s}^2 + \frac{m}{m + 1} (Q^2 + A\kappa^2\tilde{s}^2) \right)^{-1/4} \\ & \times \int_0^\infty \frac{t^2}{t^2 + A^2\kappa^2\tilde{s}^2} \left(\frac{m(m + 2)}{(m + 1)^2} t^2 + \frac{m}{m + 1} (Q^2 + A\kappa^2\tilde{s}^2) \right)^{-1/4} \\ & \times \frac{|\tilde{s}|t}{[\tilde{s}^2 + t^2 + \frac{m}{1+m} (Q^2 + A\kappa^2\tilde{s}^2)]^2} \frac{\ln(1 - \lambda_1) - \ln(1 - \lambda_2)}{\lambda_2 - \lambda_1} \, dt \end{aligned} \tag{7.6}$$

where

$$\lambda_1 = \frac{4A^2\kappa^2t^2\tilde{s}^2}{(t^2 + A^2\kappa^2\tilde{s}^2)^2}, \quad \lambda_2 = \frac{4}{(m + 1)^2} \frac{t^2\tilde{s}^2}{(t^2 + \tilde{s}^2 + \frac{m}{m+1} (Q^2 + A\kappa^2\tilde{s}^2))^2} \tag{7.7}$$

By the overall scale invariance, we can set $\tilde{s}^2 = 1$, and hence we are left with two parameters to optimize over, $Q \geq 0$ and $\kappa \geq 0$ or, equivalently, $0 \leq b \leq 1/A = 2 + m$.

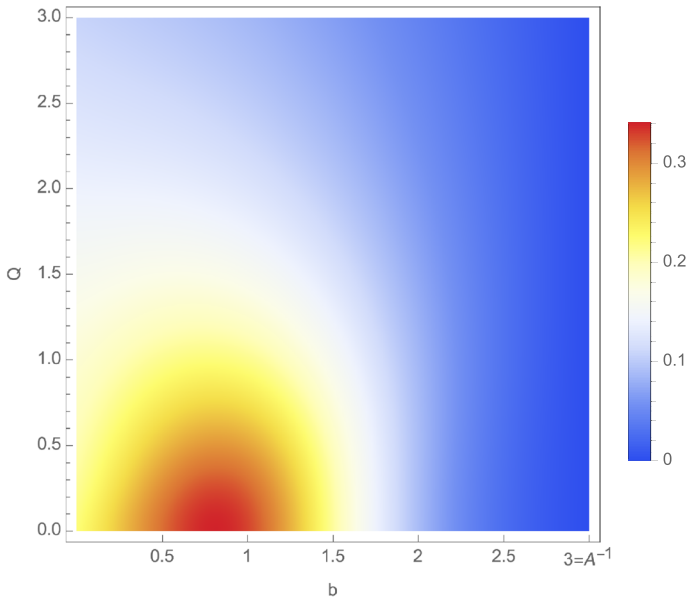


Fig. 2. Numerical evaluation of the expression (7.6) (for $\tilde{s}^2 = 1$), whose maximal value is $\Lambda(1)$. The maximum is attained at $Q = 0$ and $b \approx 0.82$, and has a value $\Lambda(1) \approx 0.34$

It is not difficult to see that (7.6) tends to zero as $Q \rightarrow \infty$ (uniformly in b) and thus the optimization is effectively over a compact set. The result of a numerical integration of (7.6) in the case $m = 1$ is shown in Fig. 2. The supremum is attained at $Q = 0$ and $b \approx 0.82$, and equals $\Lambda(1) \approx 0.34$. In particular, it is less than 1. Moreover, the numerical evaluation yields $\Lambda(m) < 1$ for all $m \geq 0.36$, i.e., the critical mass for stability is less than 0.36, as shown in Fig. 1.

The same analysis applies to $\Lambda_\beta(m)$ in (2.15). For $\beta = 1$ and $\beta = 2$, the graph of these functions is plotted in Fig. 1.

8. Proof of Proposition 1

Let $\psi \in D(\mathcal{H}_\alpha)$, and consider the partial Fourier transform

$$\begin{aligned} \eta(P, k_1, \dots, k_{N-1}, r) &= \frac{1}{(2\pi)^{3/2}} \int_{\mathbb{R}^3} \hat{\psi} \left(\frac{m}{1+m} P + q, k_1, \dots, k_{N-1}, \frac{1}{1+m} P - q \right) e^{ir \cdot q} dq \end{aligned} \tag{8.1}$$

With the aid of (2.25) and (2.28)–(2.33) we can write

$$\begin{aligned} \eta(P, k_1, \dots, k_{N-1}, r) &= \left(\frac{2\pi^2}{|r|} + \alpha \right) \frac{2m}{m+1} \frac{(-1)^{N+1}}{(2\pi)^{3/2}} \hat{\xi}(P, k_1, \dots, k_{N-1}) \\ &\quad + \sum_{j=1}^3 \kappa_j(P, k_1, \dots, k_{N-1}, r) \end{aligned} \tag{8.2}$$

where

$$\begin{aligned} \kappa_1(P, k_1, \dots, k_{N-1}, r) &= \frac{1}{(2\pi)^{3/2}} \int_{\mathbb{R}^3} \hat{\phi} \left(\frac{m}{1+m} P + q, k_1, \dots, k_{N-1}, \frac{1}{1+m} P - q \right) \left(e^{ir \cdot q} - 1 \right) dq \end{aligned} \tag{8.3}$$

and

$$\begin{aligned} \kappa_2(P, k_1, \dots, k_{N-1}, r) &= \frac{1}{(2\pi)^{3/2}} \int_{\mathbb{R}^3} \mathcal{G} \left(\frac{m}{1+m} P + q, k_1, \dots, k_{N-1}, \frac{1}{1+m} P - q \right) \left(e^{ir \cdot q} - 1 \right) \\ &\times \sum_{j=1}^{N-1} (-1)^{j+1} \hat{\xi} \left(\frac{m}{1+m} P + q + k_j, k_1, \dots, k_{j-1}, k_{j+1}, \dots, k_{N-1}, \frac{1}{1+m} P - q \right) dq \end{aligned} \tag{8.4}$$

Introducing the function $f(t) = t^{-1}(e^{-t} - 1 + t)$ for $t > 0$ we further have

$$\begin{aligned} \kappa_3(P, k_1, \dots, k_{N-1}, r) &= \frac{(-1)^{N+1}}{(2\pi)^{3/2}} f \left(\frac{|r|}{2\pi^2} \frac{1+m}{2m} \mathcal{L}(P, k_1, \dots, k_{N-1}) \right) \\ &\times \mathcal{L}(P, k_1, \dots, k_{N-1}) \hat{\xi}(P, k_1, \dots, k_{N-1}) \end{aligned} \tag{8.5}$$

Since $\phi \in H^2(\mathbb{R}^{3(N+1)})$, one readily checks that $\lim_{r \rightarrow 0} \|\kappa_1(\cdot, r)\|_{L^2(\mathbb{R}^{3N})} = 0$. Moreover, since $\xi \in H^1(\mathbb{R}^{3N})$ by assumption, $\lim_{r \rightarrow 0} \|\kappa_3(\cdot, r)\|_{L^2(\mathbb{R}^{3N})} = 0$ by dominated convergence, using $\lim_{t \rightarrow 0} f(t) = 0$. The same holds true for κ_2 if we can show that

$$\begin{aligned} &\int_{\mathbb{R}^3} \mathcal{G} \left(\frac{m}{1+m} P + q, k_1, \dots, k_{N-1}, \frac{1}{1+m} P - q \right) \\ &\times \left| \hat{\xi} \left(\frac{m}{1+m} P + q + k_1, k_2, \dots, k_{N-1}, \frac{1}{1+m} P - q \right) \right| dq \end{aligned} \tag{8.6}$$

is an $L^2(\mathbb{R}^{3N})$ function. For this purpose, pick a function $v \in L^2(\mathbb{R}^3) \otimes L^2_{\text{as}}(\mathbb{R}^{3(N-1)})$ and integrate the expression (8.6) against $v(P, k_1, \dots, k_{N-1})$. After a change of integration variables, this gives

$$\begin{aligned} &\int_{\mathbb{R}^{3(N+1)}} v(k_0 + k_N, k_1, \dots, k_{N-1}) \mathcal{G}(k_0, k_1, \dots, k_N) \\ &\times \left| \hat{\xi}(k_0 + k_1, k_2, \dots, k_N) \right| dk_0 dk_1 \cdots dk_N \end{aligned} \tag{8.7}$$

Since $\xi \in H^1(\mathbb{R}^{3N})$ by assumption, Lemma 1 (for $\beta = 1$) implies that (8.7) is finite. This shows that also $\|\kappa_2(\cdot, r)\|_{L^2(\mathbb{R}^{3N})}$ goes to 0 as $r \rightarrow 0$, and thus completes the proof of Proposition 1. \square

9. Proof of Theorem 3

We start with n_\uparrow . For $\psi = \phi + \mathcal{G}\xi \in D(\mathcal{H}_\alpha)$, we have

$$\begin{aligned}
 k^2 n_\uparrow(k) &= \frac{C}{|k - p_\uparrow|^2} \\
 &= k^2 \int_{\mathbb{R}^{3N}} |\hat{\phi}(k, k_1, k_2, \vec{k})|^2 dk_1 dk_2 d\vec{k} \\
 &\quad - k^2 N(N-1) \int_{\mathbb{R}^{3N}} \mathcal{G}(k, k_1, k_2, \vec{k})^2 \hat{\xi}^*(k+k_1, k_2, \vec{k}) \hat{\xi}(k+k_2, k_1, \vec{k}) dk_1 dk_2 d\vec{k} \\
 &\quad + N \int_{\mathbb{R}^{3N}} \left(k^2 \mathcal{G}(k, k_1, k_2, \vec{k})^2 - \left(\frac{2m}{m+1} \right)^2 \frac{1}{|k - p_\uparrow|^2} \right) |\hat{\xi}(k+k_1, k_2, \vec{k})|^2 dk_1 dk_2 d\vec{k} \\
 &\quad + 2k^2 N \operatorname{Re} \int_{\mathbb{R}^{3N}} \hat{\phi}^*(k, k_1, k_2, \vec{k}) \mathcal{G}(k, k_1, k_2, \vec{k}) \hat{\xi}(k+k_1, k_2, \vec{k}) dk_1 dk_2 d\vec{k} \tag{9.1}
 \end{aligned}$$

where $\vec{k} \in \mathbb{R}^{3(N-2)}$, as before. We write the right side as $\sum_{j=1}^4 M_j^\uparrow(k)$, with M_j^\uparrow corresponding to the term on the j th line on the right side. The first term M_1^\uparrow is clearly in $L^1(\mathbb{R}^3)$. Using (2.24) the second term can be bounded as

$$|M_2^\uparrow(k)| \leq N(N-1) \int_{\mathbb{R}^{3N}} \frac{4m}{k_1^2 + k_2^2} |\hat{\xi}(k+k_1, k_2, \vec{k})| |\hat{\xi}(k+k_2, k_1, \vec{k})| dk_1 dk_2 d\vec{k} \tag{9.2}$$

After integrating over k and using the Cauchy-Schwarz inequality for the (k, \vec{k}) integration, we get

$$\begin{aligned}
 &\int_{\mathbb{R}^3} |M_2^\uparrow(k)| dk \\
 &\leq N(N-1) \int_{\mathbb{R}^{3N}} \frac{4m}{k_1^2 + k_2^2} \|\hat{\xi}(\cdot, k_1)\|_{L^2(\mathbb{R}^{3(N-1)})} \|\hat{\xi}(\cdot, k_2)\|_{L^2(\mathbb{R}^{3(N-1)})} dk_1 dk_2 \\
 &\leq 4mcN(N-1)^2 \|\xi\|_{H^{1/2}(\mathbb{R}^{3N})}^2 \tag{9.3}
 \end{aligned}$$

where c equals the norm of the operator with integral kernel $|k_1|^{-1/2} |k_2|^{-1/2} (k_1^2 + k_2^2)^{-1}$, which can easily be shown to be finite (and, in fact, equals $2\pi^2$ [15, Lemma 2.1]).

Next we shall consider $M_3^\uparrow(k)$, which we rewrite as

$$\begin{aligned}
 M_3^\uparrow(k) &= N \int_{\mathbb{R}^{3N}} \left(k^2 \mathcal{G}(k, k_1 - k, k_2, \vec{k})^2 - \left(\frac{2m}{m+1} \right)^2 \frac{1}{|k - p_\uparrow|^2} \right) \\
 &\quad \times |\hat{\xi}(k_1, k_2, \vec{k})|^2 dk_1 dk_2 d\vec{k} \tag{9.4}
 \end{aligned}$$

Since $\xi \in L^2(\mathbb{R}^{3N})$, M_3^\uparrow is clearly in $L^1_{\text{loc}}(\mathbb{R}^3)$ and we only have to investigate its behavior for large k . If we write

$$\begin{aligned}
 &k^2 \mathcal{G}(k, k_1 - k, k_2, \vec{k})^2 - \left(\frac{2m}{m+1} \right)^2 \frac{1}{|k - p_\uparrow|^2} \\
 &= \left(\frac{2m}{m+1} \right)^2 \frac{2}{|k|^4} k \cdot \left(\frac{2m}{m+1} k_1 - p_\uparrow \right) + R_\uparrow(k, k_1, k_2, \vec{k}) \tag{9.5}
 \end{aligned}$$

the first term on the right side gives zero after integration when inserted in (9.4), by the definition of p_\uparrow in (2.40). That is,

$$M_3^\uparrow(k) = N \int_{\mathbb{R}^{3N}} R_\uparrow(k, k_1, k_2, \vec{k}) |\hat{\xi}(k_1, k_2, \vec{k})|^2 dk_1 dk_2 d\vec{k} \quad (9.6)$$

Moreover, in the region where $|k|^2 \geq \text{const}(\mu + p_\uparrow^2)$ we have

$$\begin{aligned} & |R_\uparrow(k, k_1, k_2, \dots, k_N)| \\ & \leq \text{const} \frac{1}{|k|^3} \left(\mu + p_\uparrow^2 + \sum_{j=1}^N k_j^2 \right)^{1/2} \min \left\{ 1, \frac{1}{|k|} \left(\mu + p_\uparrow^2 + \sum_{j=1}^N k_j^2 \right)^{1/2} \right\} \end{aligned} \quad (9.7)$$

for suitable constants. If we integrate R_\uparrow over k in this region we thus obtain an expression that is bounded from above by $\text{const}(\mu + p_\uparrow^2 + \sum_{j=1}^N k_j^2)^{1/2} \ln(1 + \mu + p_\uparrow^2 + \sum_{j=1}^N k_j^2)$, and we conclude, in particular, that $\|M_3^\uparrow\|_{L^1(\mathbb{R}^3)} \leq \text{const} \|\xi\|_{H^1(\mathbb{R}^{3N})}^2$. Finally, using the simple pointwise bound

$$|M_4^\uparrow(k)| \leq 4mN \|\hat{\phi}(k, \cdot)\|_{L^2(\mathbb{R}^{3N})} \|\xi\|_{L^2(\mathbb{R}^{3N})} \quad (9.8)$$

and the assumption that $\phi \in H^2(\mathbb{R}^{3(N+1)})$, the Cauchy-Schwarz inequality readily implies that $M_4^\uparrow \in L^1(\mathbb{R}^3)$. This concludes the proof that $k^2 n_\uparrow(k) - \mathcal{C}|k - p_\uparrow|^{-2}$ is integrable.

Similarly we have for n_\downarrow

$$\begin{aligned} k^2 n_\downarrow(k) - \frac{\mathcal{C}}{|k - p_\downarrow|^2} &= \sum_{j=1}^7 M_j^\downarrow(k) = \\ &= Nk^2 \int_{\mathbb{R}^{3N}} |\hat{\phi}(k_0, k, k_2, \mathbf{k})|^2 dk_0 dk_2 d\mathbf{k} \\ &\quad - k^2 N(N-1)(N-2) \int_{\mathbb{R}^{3N}} \mathcal{G}(k_0, k, k_2, \dots, k_N)^2 \hat{\xi}^*(k_0 + k_2, k, k_3, \dots, k_N) \\ &\quad \quad \quad \times \hat{\xi}(k_0 + k_3, k, k_2, k_4, \dots, k_N) dk_0 dk_2 \dots dk_N \\ &\quad - 2k^2 N(N-1) \int_{\mathbb{R}^{3N}} \mathcal{G}(k_0, k, k_2, \mathbf{k})^2 \hat{\xi}^*(k_0 + k, k_2, \mathbf{k}) \hat{\xi}(k_0 + k_2, k, \mathbf{k}) dk_0 dk_2 d\mathbf{k} \\ &\quad + k^2 N(N-1) \int_{\mathbb{R}^{3N}} \mathcal{G}(k_0, k, k_2, \mathbf{k})^2 |\hat{\xi}(k_0 + k_2, k, \mathbf{k})|^2 dk_0 dk_2 d\mathbf{k} \\ &\quad + N \int_{\mathbb{R}^{3N}} \left(k^2 \mathcal{G}(k_0, k, k_2, \mathbf{k})^2 - \left(\frac{2m}{m+1} \right)^2 \frac{1}{|k - p_\downarrow|^2} \right) |\hat{\xi}(k_0 + k, k_2, \mathbf{k})|^2 dk_0 dk_2 d\mathbf{k} \\ &\quad + 2k^2 N \text{Re} \int_{\mathbb{R}^{3N}} \hat{\phi}^*(k_0, k, k_2, \mathbf{k}) \mathcal{G}(k_0, k, k_2, \mathbf{k}) \hat{\xi}(k_0 + k, k_2, \mathbf{k}) dk_0 dk_2 d\mathbf{k} \\ &\quad + 2k^2 N(N-1) \text{Re} \int_{\mathbb{R}^{3N}} \hat{\phi}^*(k_0, k, k_2, \mathbf{k}) \mathcal{G}(k_0, k, k_2, \mathbf{k}) \hat{\xi}(k_0 + k_2, k, \mathbf{k}) dk_0 dk_2 d\mathbf{k} \quad (9.9) \end{aligned}$$

The terms $M_1^\downarrow, M_2^\downarrow, M_3^\downarrow, M_5^\downarrow$ and M_6^\downarrow can be treated in the same way as the analogous terms in (9.1) above. Eq. (9.6) holds with M_5^\downarrow in place of M_3^\uparrow with R_\uparrow replaced by

$$R_\downarrow(k, k_1, k_2, \vec{k}) = k^2 \mathcal{G}(k_1 - k, k, k_2, \vec{k})^2 - \left(\frac{2m}{m+1}\right)^2 \frac{1}{|k - p_\downarrow|^2} - \left(\frac{2m}{m+1}\right)^2 \frac{2}{|k|^4} k \cdot \left(\frac{2}{m+1} k_1 - p_\downarrow\right) \tag{9.10}$$

which also satisfies the bound (9.7). The expression M_4^\downarrow equals

$$M_4^\downarrow(k) = k^2 N(N-1) \int_{\mathbb{R}^{3N}} \mathcal{G}(k_0 - k_2, k, k_2, \vec{k})^2 |\hat{\xi}(k_0, k, \vec{k})|^2 dk_0 dk_2 d\vec{k} \tag{9.11}$$

Performing the integration over k_2 , one readily checks that

$$M_4^\downarrow(k) \leq \text{const } |k| N(N-1) \int_{\mathbb{R}^{3N}} |\hat{\xi}(k_0, k, \vec{k})|^2 dk_0 d\vec{k} \tag{9.12}$$

which is in $L^1(\mathbb{R}^3)$ since $\xi \in H^{1/2}(\mathbb{R}^{3N})$. Finally, using Cauchy-Schwarz in (k, k_2, \vec{k}) ,

$$\int_{\mathbb{R}^3} |M_7^\downarrow(k)| dk \leq 4N(N-1) \|\xi\|_{L^2(\mathbb{R}^{3N})} \int_{\mathbb{R}^3} \|\hat{\phi}(k_0, \cdot)\|_{L^2(\mathbb{R}^{3N})} dk_0 \tag{9.13}$$

which is finite for $\phi \in H^2(\mathbb{R}^{3(N-1)})$, as remarked above. We conclude, therefore, that also $k^2 n_\downarrow(k) - \mathcal{C}|k - p_\downarrow|^{-2}$ is integrable.

Since all the terms in (9.1) and (9.9) are integrable, we can do the integration over k term by term. For all the terms except M_3^\uparrow and M_5^\downarrow , we have actually shown that the L^1 -property holds even if the respective integrands are replaced by their absolute value, and hence we can freely use Fubini’s theorem for these terms. In the form (9.6) (and the analogous expression for M_5^\downarrow) the same applies to M_3^\uparrow and M_5^\downarrow , in fact.

For the norm of ψ , we shall write

$$\begin{aligned} \|\psi\|_{L^2(\mathbb{R}^{3(N+1)})}^2 &= \sum_{j=1}^4 n_j = \|\phi\|_{L^2(\mathbb{R}^{3(N+1)})}^2 + 2 \text{Re}\langle \phi | \mathcal{G}\xi \rangle \\ &\quad - N(N-1) \int_{\mathbb{R}^{3N}} \mathcal{G}(k_0, k_1, k_2, \vec{k})^2 \hat{\xi}^*(k_0 + k_1, k_2, \vec{k}) \hat{\xi}(k_0 + k_2, k_1, \vec{k}) dk_0 dk_1 dk_2 d\vec{k} \\ &\quad + N \int_{\mathbb{R}^{3N}} \mathcal{G}(k_0, k_1, k_2, \vec{k})^2 |\hat{\xi}(k_0 + k_1, k_2, \vec{k})|^2 dk_0 dk_1 dk_2 d\vec{k} \end{aligned} \tag{9.14}$$

We have

$$\int_{\mathbb{R}^3} \left(\frac{1}{2m} M_1^\uparrow(k) + \frac{1}{2} M_1^\downarrow(k) \right) dk + \mu n_1 = \left\langle \phi \left| -\frac{1}{2m} \Delta_{x_0} - \frac{1}{2} \sum_{i=1}^N \Delta_{x_i} + \mu \right| \phi \right\rangle \tag{9.15}$$

and

$$\int_{\mathbb{R}^3} \left[\frac{1}{2m} M_2^\uparrow(k) + \frac{1}{2} \left(M_2^\downarrow(k) + M_3^\downarrow(k) \right) \right] dk + \mu n_3 = -N \mathcal{T}_{\text{off}}(\xi) \tag{9.16}$$

Moreover, we claim that

$$\int_{\mathbb{R}^3} \left[\frac{1}{2m} M_3^\uparrow(k) + \frac{1}{2} \left(M_4^\downarrow(k) + M_5^\downarrow(k) \right) \right] dk + \mu n_4 = -N \mathcal{T}_{\text{diag}}(\xi) \tag{9.17}$$

To see this, note that we can replace $M_3^\uparrow(k)$ by its symmetrized version $\frac{1}{2}(M_3^\uparrow(k) + M_3^\uparrow(-k))$, and likewise for M_5^\downarrow . Then (9.17) follows from the fact that

$$\begin{aligned} & \int_{\mathbb{R}^3} \left(\frac{1}{4m} (R_\uparrow(k, k_1, \dots, k_N) + R_\uparrow(-k, k_1, \dots, k_N)) \right. \\ & \quad + \frac{1}{4} (R_\downarrow(k, k_1, \dots, k_N) + R_\downarrow(-k, k_1, \dots, k_N)) \\ & \quad \left. + \frac{1}{2} \sum_{j=2}^N k_j^2 \mathcal{G}(k_1 - k, k, k_2, \dots, k_N)^2 \right) dk = -\mathcal{L}(k_1, \dots, k_N) \end{aligned} \tag{9.18}$$

which, in turn, uses that

$$\int_{\mathbb{R}^3} \left(\frac{2}{|k|^2} - \frac{1}{|k - p|^2} - \frac{1}{|k + p|^2} \right) dk = 0 \tag{9.19}$$

for any $p \in \mathbb{R}^3$ (which can be proved, e.g., by computing the Fourier transform). Finally,

$$\begin{aligned} & \int_{\mathbb{R}^3} \left[\frac{1}{2m} M_4^\uparrow(k) + \frac{1}{2} \left(M_6^\downarrow(k) + M_7^\downarrow(k) \right) \right] dk + \mu n_2 \\ & \quad = 2N \operatorname{Re} \int \hat{\phi}^*(k_0, k_1 - k_0, k_2, \vec{k}) \hat{\xi}(k_1, k_2, \vec{k}) dk_0 dk_1 dk_2 d\vec{k} \end{aligned} \tag{9.20}$$

In Fourier space, the boundary condition (2.33) satisfied by ϕ reads

$$\int \hat{\phi}(k_0, k_1 - k_0, k_2, \vec{k}) dk_0 = \left(\frac{2m}{m+1} \alpha \hat{\xi} + \widehat{\Gamma} \hat{\xi} \right) (k_1, k_2, \vec{k}) \tag{9.21}$$

and hence

$$(9.20) = 2N \left(\mathcal{T}_{\text{diag}}(\xi) + \mathcal{T}_{\text{off}}(\xi) + \frac{2m}{m+1} \alpha \|\hat{\xi}\|_{L^2(\mathbb{R}^{3N})}^2 \right) \tag{9.22}$$

A combination of (9.15), (9.16), (9.17), (9.22) with (2.26) establishes (2.42) and thus completes the proof of Theorem 3. \square

Remark 2. The proof of Theorem 3 does not actually make use of the assumption $\xi \in H^1(\mathbb{R}^{3N})$, it is only used that

$$\int_{\mathbb{R}^{3N}} \left(1 + \sum_{j=1}^N |k_j|^2 \right)^{1/2} \ln \left(2 + \sum_{j=1}^N |k_j|^2 \right) |\hat{\xi}(k_1, \dots, k_N)|^2 dk_1 \cdots dk_N < \infty \tag{9.23}$$

By Theorem 2, this is actually the case if $\Lambda_0(m) = 2\Lambda(m) < 1$ (instead of $\Lambda_1(m) < 1$) since then, by continuity, $\Lambda_\beta(m) < 1$ for some $\beta > 0$, and hence $\xi \in H^{(1+\beta)/2}(\mathbb{R}^{3N})$.

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